



Introduction to julia

Parallel Computing Revisited

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A language for both prototyping and performance



We try to cover the following

- Examples of using parallelization enabled linear algebra libraries
- Examples of parallel processing support via **Distributed**
- Examples of using distributed arrays (**DistributedArrays**) and shared arrays (**SharedArrays**)
- A example of using threads

What will **NOT** be covered

- Using Julia in Jupyter Notebook
- Threaded computing details (a separate talk)
- MPI and others

This is not a tutorial, but rather a collection of pointers for ones to explore.



Using libraries



Parallel computing: Implicit parallelism

Example: Matrix-vector operations via OpenBLAS

We run this simple code first

```
n = 5000
```

```
A = randn(n,n)
```

```
B = randn(n,n)
```

```
C = zeros(n,n)
```

using LinearAlgebra

```
for i=1:4
```

```
    @time C = A*B
```

```
end
```

And then set environment variable

```
export OMP_NUM_THREADS=4
```

and run it again to see if there's any performance changes.

Do not spawn julia threads!



Running on multiple processors



Parallel computing: Starting multiple processes

Launching from command line when starting julia

```
julia -p 8
```

or

```
julia --machine-file hostfile
```

Launching from within a julia process

```
using Distributed
```

```
# Start extra 8 processes to have 9 in total
```

```
addprocs(8)
```

*On clusters using a scheduler, dynamically creating or increasing the number of processes is **DISCOURAGED**.*



Launching from command line when starting julia

```
julia -p 8
```

or

```
julia --machine-file hostfile
```

Launching on a cluster

```
#!/bin/bash
#SBATCH --ntasks=64          # number of MPI
processes
#SBATCH --cpus-per-task=1
#SBATCH --mem-per-cpu=1024M
#SBATCH --time=0-00:05
#SBATCH --account=def-bge
#SBATCH --job-name=hello
#SBATCH --output=hello.log

srun hostname -s > hostfile
sleep 5
julia --machine-file ./hostfile ./hello.jl
```



Parallel computing: Programming model

Two simple mechanisms

- @everywhere
- @spawn, @spawnat



Parallel computing: Broadcasting a value to all processes

Broadcast a value to all processes

using Distributed

```
@everywhere x = 12345 # This works
```

X0 = 12345 # X0 is a local variable to the main process

```
@everywhere x = x0 # This MAY fail, as x0 is local, check the following
```

```
@everywhere println(x)
```

```
@everywhere x = $x0 # This works! By "copying" x0 value
```



Execute a locally defined function

using Distributed

The scope of this function is within this process

```
function showid()
  println("My ID: ", myid())
end
```

This is likely to fail on other processes

```
@everywhere showid()
```

Execute a globally defined function

using Distributed

This function is defined on every process

```
@everywhere function showid()
  println("My ID: ", myid())
end
```

Execute this procedure on every process

```
@everywhere showid()
```



Parallel computing: Executing a function on all processes

Execute a locally defined function
using Distributed

```
# The scope of this function is within this process
```

```
function showid()
```

```
    println("My ID: ", myid())
```

```
end
```

```
# This is likely to fail on other processes
```

```
@everywhere showid()
```

Execute a globally defined function
using Distributed

```
# This function is defined on every process
```

```
@everywhere function showid()
```

```
    println("My ID: ", myid())
```

```
end
```

```
# Execute this procedure on every process
```

```
@everywhere showid()
```

@everywhere *stmt*



Parallel computing: Executing a procedure remotely

Exercise: Type and run the following code

using Distributed

```
println("Number of cores: ", nprocs())
```

```
println("Number of workers: ", nworkers())
```

```
# Fetch the ID of each worker and host the worker running on
```

```
for i in workers()
```

```
    id, pid, host = fetch(@spawnat i (myid(), getpid(), gethostname()))
```

```
    println(id, " ", pid, " Hello from ", host)
```

```
end
```



Parallel computing: Executing a procedure remotely

Julia uses the concept "future" referring to the remote execution.

To run a procedure on an automatically chosen process

```
f = @spawn (x.^2, myid())
```

To run a procedure on a specific process n

```
f = @spawnat n (x.^2, myid())
```

To get the result, one needs to "fetch" it by the reference.

```
fetch(f)
```



Parallel computing: Executing a procedure remotely

Note the performance difference in the following two calls

```
n=10_000  
A=randn(n,n);
```

```
@time fetch(@spawnat :any sum(A.^2)) # Involves copying A to remote process
```

vs.

```
n=10_000  
@time fetch(@spawnat :any sum(randn(n,n).^2)) # No data copy
```



Parallel computing: Executing a procedure remotely

Julia uses the concept "future" referring to the remote execution.

To run a procedure on an automatically chosen process

```
f = @spawn (x.^2, myid())
```

To run a procedure on a specific process p

```
f = @spawnat p (x.^2, myid())
```

To get the result, one needs to "fetch" it by the reference.

```
fetch(f)
```

@spawn stmt

@spawnat proc stmt

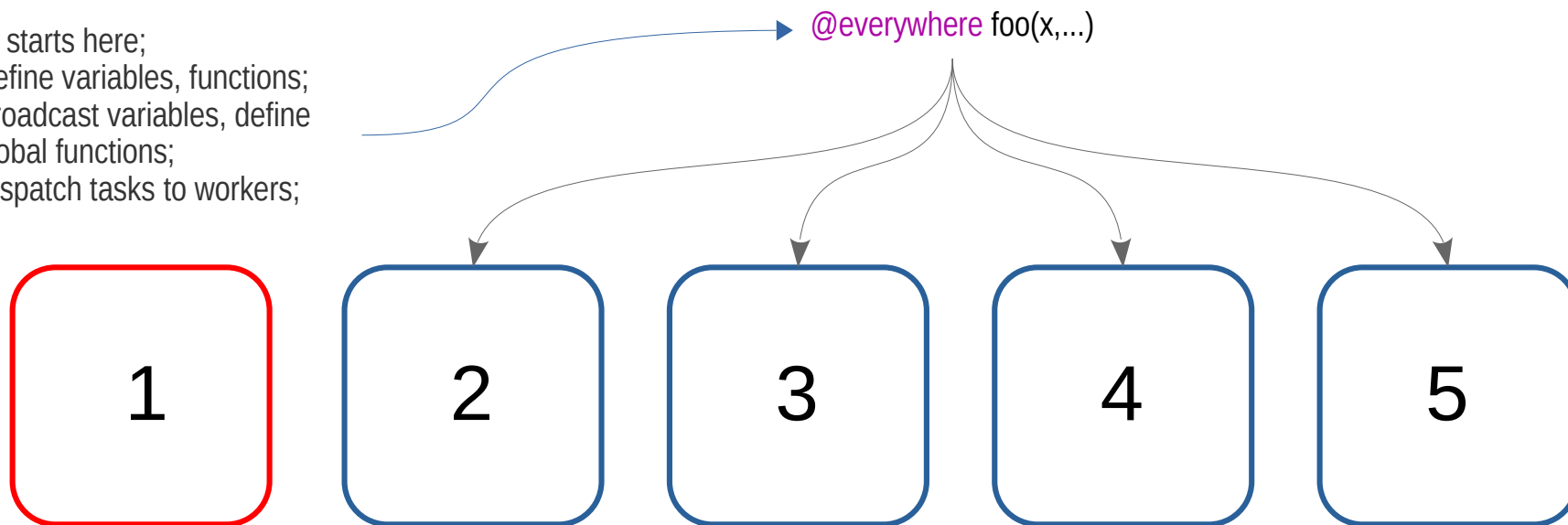


Parallel computing: Programming model

Julia always uses $1+p$ processes: A control or Main process, plus p Worker processes

Code starts here;

- Define variables, functions;
- Broadcast variables, define global functions;
- Dispatch tasks to workers;



Tasks are dispatched and computed on workers, like jobs are done on compute nodes.

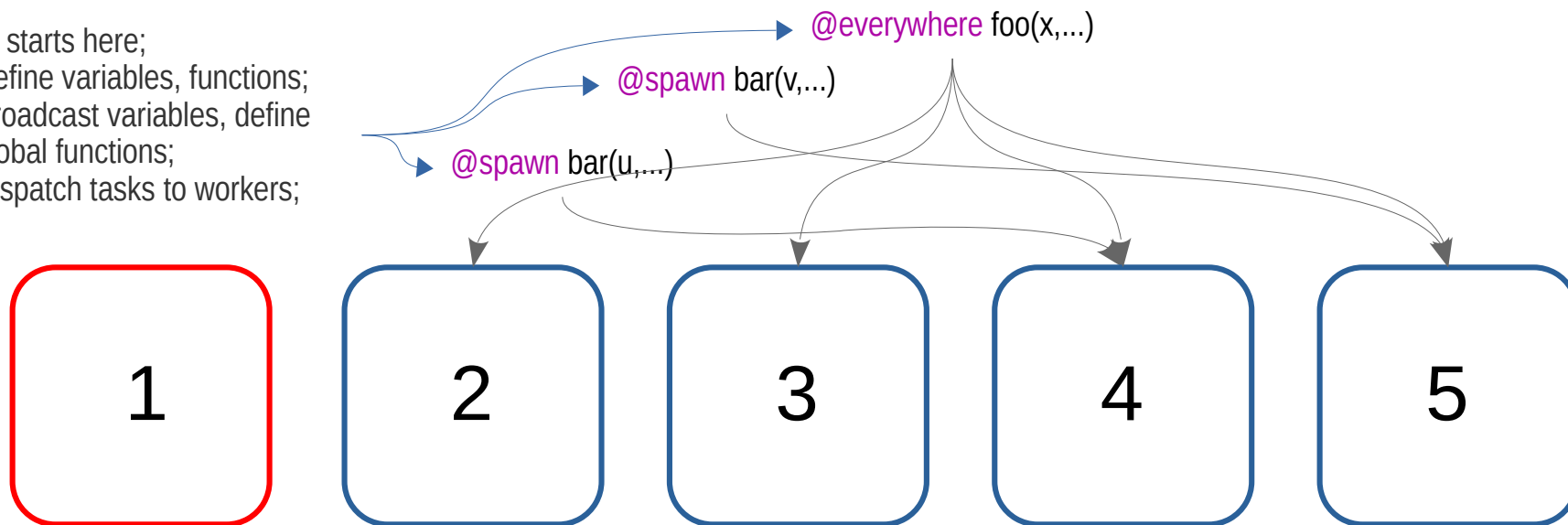


Parallel computing: Programming model

Julia always uses $1+p$ processes: A control or Main process, plus p Worker processes

Code starts here;

- Define variables, functions;
- Broadcast variables, define global functions;
- Dispatch tasks to workers;



Tasks are dispatched and computed on workers, like jobs are done on compute nodes.



Parallel computing: Placing a remote call

Asynchronous call, non-blocking, returns immediately

```
f = remotecall( maximum, WorkerPool(workers()), x )
```

To get the result *call* *where* *var*

```
r = fetch(f)
```

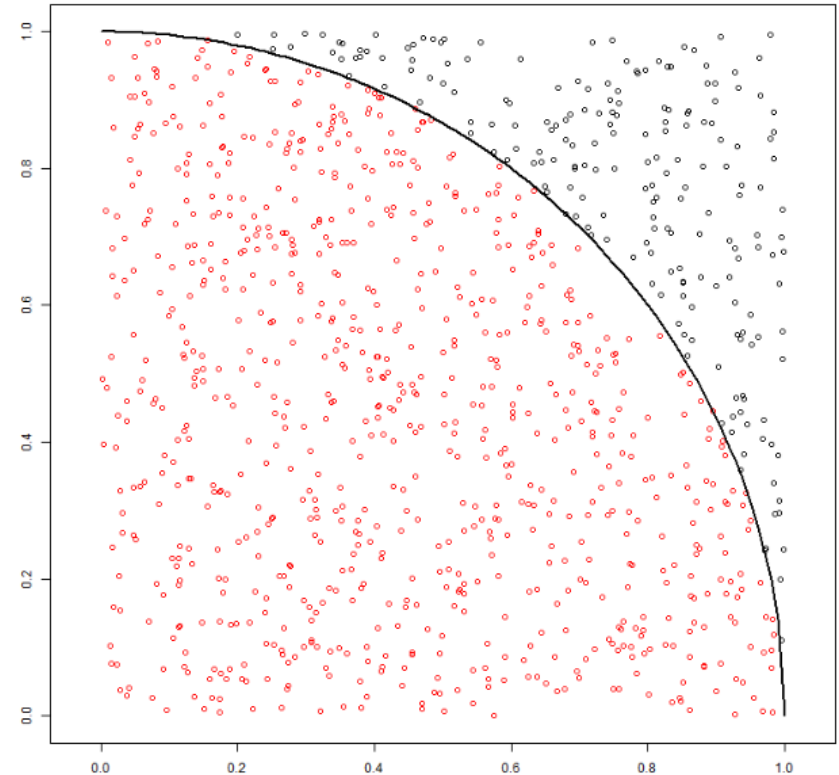
Synchronous call, combines remotecall() and fetch()

```
r = remotecall_fetch(maximum,WorkerPool(workers()),x)
```



Example: We compute the approximation of pi by counting the points uniformly tossed inside an 1/4 circle vs total number of points over the unit square (See Marc Marano Maza 2017).

$$\frac{\frac{1}{4}\pi a^2}{a^2} = \frac{n_{\text{in}}}{n} \implies \pi \approx 4 \frac{n_{\text{in}}}{n}$$



Create a file "pi_dist.jl", define a function that counts the number of points falling inside the circle

```
function points_inside_circle(n)
    n_in = 0
    for i=1:n
        x, y=rand(), rand()
        n_in += (x*x + y*y) <= 1
    end
    return n_in
end
```

In the same file, define a function wrapper that computes the approximation of pi in parallel

```
function pi_p(n)
    p = nworkers()
    n_in = @distributed (+) for i=1:p # A reduction call
        points_inside_circle(n/p)
    end
    return 4*n_in/n # The approximation of pi
end
```

This function executes on multiple cores in parallel and collects the result by reduction

@distributed op procedure



Parallel computing: Calculating the approximation of pi

Create a file "pi_dist.jl", define a function that counts the number of points falling inside the circle

```
function points_inside_circle(n)
    n_in = 0
    for i=1:n
        x, y = rand(), rand()
        n_in += (x*x + y*y) <= 1
    end
    return n_in
end
```

In the same file, define a function wrapper that computes the approximation of pi in parallel

```
function pi_p(n)
    p = nworkers()
    n_in = @distributed (+) for i=1:p # A reduction call
        points_inside_circle(n/p)
    end
    return 4*n_in/n # The approximation of pi
end
```

@distributed op procedure

N.B. This function executes on multiple cores in parallel and collects the result by reduction

@distributed op procedure



Parallel computing: Calculating the approximation of pi

Now we start julia with 4 workers using command

```
julia -p 4
```

Within julia, use the commands below

```
julia> using Distributed
```

```
julia> @everywhere include("pi_dist.jl") # Load functions on all processes
```

```
julia> pi_p(1_000_000) # pi_p() is defined in file "pi_dist.jl"  
3.1419629999999996
```

Using 4 cores, for $n=1,000,000,000$, it will take about 4 to 5 seconds.



Create a file "pi_pmap.jl", define a function that estimates pi one local processor

```
function points_inside_circle(n)
    n_in = 0
    for i=1:n
        x, y=rand(), rand()
        n_in += (x*x + y*y) <= 1
    end
    return n_in
end
```

In the same file, define a function wrapper that computes the approximation of pi in parallel

```
function pi_p(n)
    p = nworkers()
    n_in = sum(pmap(x->points_inside_circle(x),
        [n/p for i=1:p]))
    return 4*n_in/n
end
```



Using distributed arrays



Parallel computing: Distributed arrays

Example: A matrix stored across 4 processes on a 2x2 Cartesian processor grid

Process 1 has the blue portion.

But it also has access to other portions stored remotely, **simply via indices.**

2	-1						
-1	2	-1					
	-1	2	-1				
		-1	2	-1			
			-1	2	-1		
				-1	2	-1	
					-1	2	
						-1	2

Suitable for handling large data sets that can NOT fit on a single machine.



Parallel computing: Distributed arrays

using Distributed, **DistributedArrays**

@**everywhere** using LinearAlgebra

@**everywhere** function aa(n)

```
la = zeros(n,n)
```

```
la[diagind(la,0)] .= 2.0
```

```
la[diagind(la,-1)] .= -1.0
```

```
la[diagind(la,1)] .= -1.0
```

```
return la
```

end

@**everywhere** function b1(n)

```
la = zeros(n,n); la[1,n] = -1.0;
```

```
return la
```

end

@**everywhere** function b2(n)

```
la = zeros(n,n); la[n,1] = -1.0;
```

```
return la
```

end

Matrix A distributed on 4 processors on a 2x2 grid

2	-1						
-1	2	-1					
	-1	2	-1				
		-1	2	-1			
			-1	2	-1		
				-1	2	-1	
					-1	2	
						-1	2



Parallel computing: Distributed arrays

```
# Call functions on workers to create local portions
```

```
d11 = @spawnat 2 aa(4)
```

```
d12 = @spawnat 3 b1(4)
```

```
d21 = @spawnat 4 b2(4)
```

```
d22 = @spawnat 5 aa(4)
```

```
# Create a distributed matrix on a 2x2 processor grid
```

```
DA = DArray(reshape([d11 d21 d12 d22],(2,2)));
```

NB:

- No (large) data communications between Main and workers;
- **d11,d12,d21,d22** are not matrices, but handles – futures. They are NOT taking up spaces;
- **DA** is NOT the whole matrix either, it's a reference;
- But one can access the entire matrix by simply using the index, e.g. `DA[5000,5050]` even though it's not local.

Matrix A distributed on 4 processors on a 2x2 grid

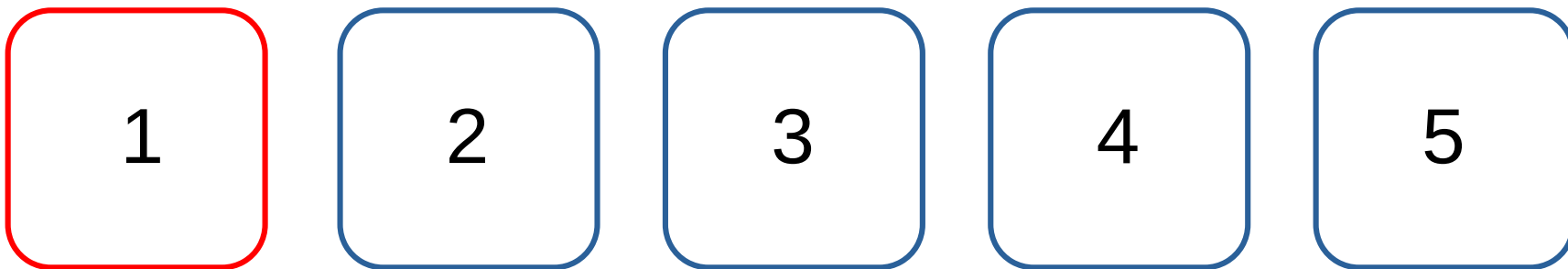
2	-1						
-1	2	-1					
	-1	2	-1				
		-1	2	-1			
			-1	2	-1		
				-1	2	-1	
					-1	2	
						-1	2



Julia always uses $1+p$ processes: A control or Main process, plus p Worker processes

`varinfo()`

← To see vars on “me”



To see vars on others



`@everywhere using InteractiveUtils`
`fetch(@spawnat p varinfo())`



Parallel computing: Distributed arrays

Call functions on workers to create local portions

n=100

d11 = @spawnat 2 aa(n)

d12 = @spawnat 3 b1(n)

d21 = @spawnat 4 b2(n)

d22 = @spawnat 5 aa(n)

Create a distributed matrix on a 2x2 processor grid

DA = DArray(reshape([d11 d12 d21 d22],(2,2)));

Examine storage on Main

varinfo()

Examining the storage on Main (Process 1):

julia> varinfo()

Name	size	summary
Base		Module
Core		Module
DA	544 bytes	200×200 DArray{Float64,2,Array{Float64,2}}
Distributed	2,021 MiB	Module
InteractiveUtils	162,090 KiB	Module
Main		Module
aa	0 bytes	typeof(aa)
ans	544 bytes	200×200 DArray{Float64,2,Array{Float64,2}}
b1	0 bytes	typeof(b1)
b2	0 bytes	typeof(b2)
d11	32 bytes	Future
d12	32 bytes	Future
d21	32 bytes	Future
d22	32 bytes	Future
n	8 bytes	Int64



Call functions on workers to create local portions

n=100

d11 = @spawnat 2 aa(n)

d12 = @spawnat 3 b1(n)

d21 = @spawnat 4 b2(n)

d22 = @spawnat 5 aa(n)

Create a distributed matrix on a 2x2 processor grid

DA = DArray(reshape([d11 d12 d21 d22],(2,2)));

Examine remote storage on Worker 2

fetch(@spawnat 2 varinfo())

Examining the storage on Worker 2:

julia> fetch(@spawnat 2 varinfo())

Name	size	summary					
Base		Module					
Core		Module					
DA	78.656 KiB	200×200 DistributedArrays.DArray{Float64,2,Array{Float64,2}}					
Distributed	1.421 MiB	Module					
Main		Module					
aa	0 bytes	typeof(aa)					
b1	0 bytes	typeof(b1)	-1	2	-1		
b2	0 bytes	typeof(b2)					
n	8 bytes	Int64		-1	2	-1	
					-1	2	-1
						-1	2



Parallel computing: Distributed arrays

```
julia> # Perform A*A directly on distributed arrays
```

```
julia> DB = zeros(8,8)
```

```
julia> DB = DA*DA
```

```
julia> # Check remote values on process 3
```

```
julia> f = @spawnat 3 DB.localpart # Remote call returns a future
```

```
julia> fetch(f)
```

```
4x4 Array{Float64,2}:
```

```
0.0 0.0 1.0 -4.0
```

```
0.0 0.0 0.0 1.0
```

```
0.0 0.0 0.0 0.0
```

```
0.0 0.0 0.0 0.0
```

```
julia> remotecall_fetch(localpart,3,DB) # Alternative
```

Result of A*A distributed on 4 processors

5	-4	1					
-4	6	-4	1				
1	-4	6	-4	1			
	1	-4	6	-4	1		
		1	-4	6	-4	1	
			1	-4	6	-4	1
				1	-4	6	-4
					1	-4	5



Parallel computing: Distributed arrays

```
julia> # Access components owned remotely
```

```
julia> DB[5:8,1:4]
```

```
4x4 view(::DArray{Float64,2,Array{Float64,2}}, 5:8, 1:4) with eltype Float64:
```

```
0.0 0.0 1.0 -4.0  
0.0 0.0 0.0 1.0  
0.0 0.0 0.0 0.0  
0.0 0.0 0.0 0.0
```

Result of A*A distributed on 4 processors

5	-4	1					
-4	6	-4	1				
1	-4	6	-4	1			
	1	-4	6	-4	1		
		1	-4	6	-4	1	
			1	-4	6	-4	1
				1	-4	6	-4
					1	-4	5



Summary:

- Define functions to be executed on workers, e.g. via `@everywhere`;
- Define global variables and broadcast to workers, e.g. via `@everywhere`;
- Create distributed arrays, by calling functions on workers, via `@spawnat` or `remotecall()`;
- Perform the operations on the distributed arrays, as if they were local;
- **This is a very different concept from the SPMD model** (often seen in scientific applications, e.g. written in MPI)



Summary (cont'd):

- So far not much self-contained functionalities are available, but only allows one to reference to global spaces by indexing to the elements.
- Each process has a global view of any distributed objects.
- It uses one-sided communication via underlying libraries (e.g. MPI). The other prominent programming language that supports global address access is Fortran.
- Support from third party libraries are expected.
- A few packages to look at
 - **Elemental** – hides the communication APIs and one can do linear algebra operations as is, such as `svdvals(A)` to get SVD values.
 - **PETSc** – contains explicit MPI like APIs.
 - **Trilinos** – contains explicit MPI like APIs.



Using shared arrays



Parallel computing: Shared arrays

Shared arrays via module SharedArrays provide a convenient way of accessing data among processes. The following creates a 5x4 integer array on each process

```
using SharedArrays
```

```
A = SharedArray{Int,2}((5,4))
```

Changes to A in one process also happen to A on other processes.



```
julia> using SharedArrays
julia> A = SharedArray{Int,2}((5,4))
5×4 SharedArray{Int64,2}:
 0 0 0 0
 0 0 0 0
 0 0 0 0
 0 0 0 0
 0 0 0 0
julia> A[:,3] = collect(11:15)
5-element Array{Int64,1}:
 11
 12
 13
 14
 15
```

```
julia> # Get the the 3rd column of A on worker 4
julia> @fetchfrom 4 A[:,3]
5-element Array{Int64,1}:
 11
 12
 13
 14
 15
```

Changes to A in one process also happen to A on other processes.



Parallel computing: Shared arrays

Remote calls

The following isn't what you intended

```
n=16
a=zeros(n) # a is local
@distributed for i=1:n
    a[i] = i
end
# a now is available on other workers!

@fetchfrom 2 a # Only see the first 4 elements are assigned values
```

NB: Surprise!

- The code results in a copy of a on each process.
- Only a portion of a gets assigned values on each process.

Using SharedArray

```
using SharedArrays
n=16
a = SharedArray{Float64}(n)
@distributed for i=1:n # Each process does a portion of the loop
    a[i] = i
end
```

NB: Each process has access to the entire chunk of the array a. In other words, a is shared among participating processes.

SharedArray objects are used on the same machine.



Summary

- Shared arrays are for the local computer only (Fortran's co-arrays can be across nodes);
- Shared arrays can be accessed via global indexing, hence convenient for parallel algorithms;
- For $A = \text{SharedArray}\{\text{Float64}, 2\}(n, n)$, the data is shared, but A is not. It's a reference and must be passed to participating workers via any of the following
 - `@everywhere function ... end` or `@everywhere var=...`
 - `@everywhere include(code_script)`
 - `@remotecall(func, worker_set, var_list)`
- Math and linear algebra operations apply to shared array objects as regular arrays;
- Lastly the diffusion example can also be implemented using distributed arrays, so it can run on clusters.



Using threads, an example



Parallel computing: Multi-threading

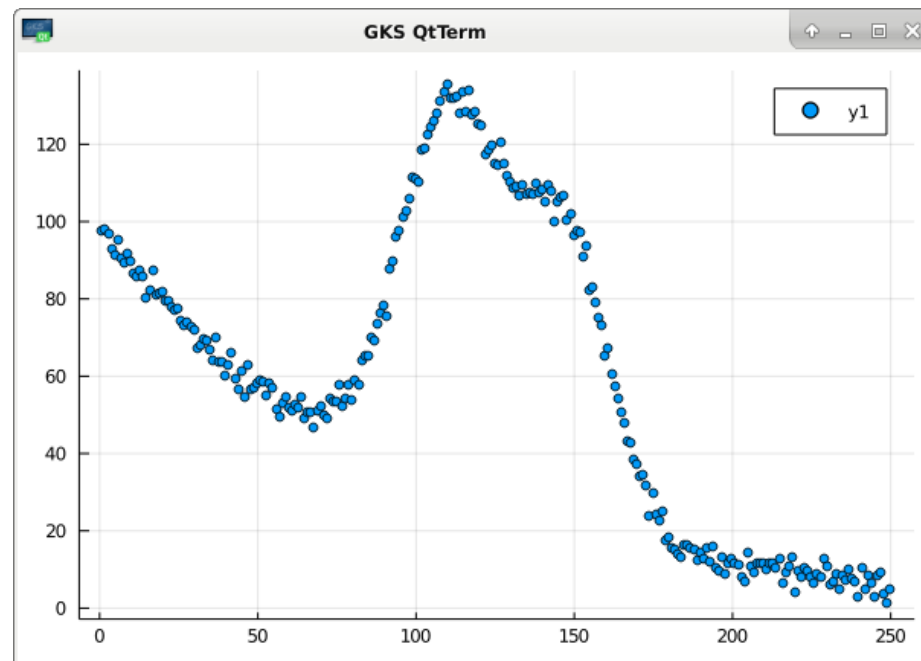
Example: Given the observation data (right, blue dots) and a model containing 8 parameters (dim $D=8$),

$$\begin{aligned}y &= f(x; p) \\ &= p_1 \exp(-p_2 x) \\ &+ p_3 \exp[-(x - p_4)^2 / p_5^2] \\ &+ p_6 \exp[-(x - p_7)^2 / p_8^2].\end{aligned}$$

find the parameters that best fit the observation data in the least squares sense[1]

$$\min_p \|y - f(x; p)\|_2.$$

This example is extracted from a work by Armin Sobhani, Ge Baolai and Pawel Pomorski.



[1] <https://www.itl.nist.gov/div898/strd/nls/data/gauss3.shtml>

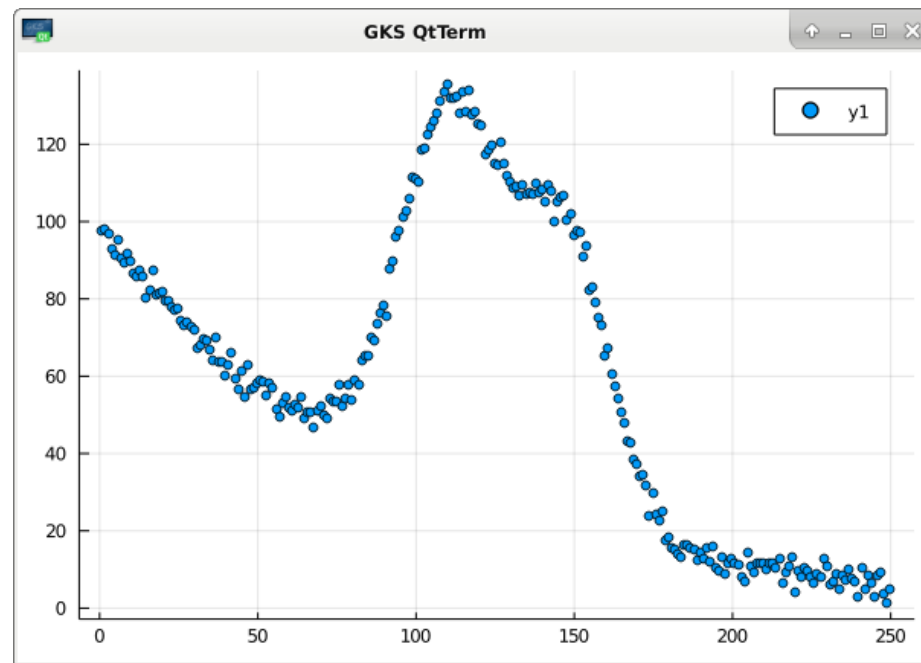
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find the parameters that best fit the observation data in the least squares sense[1]

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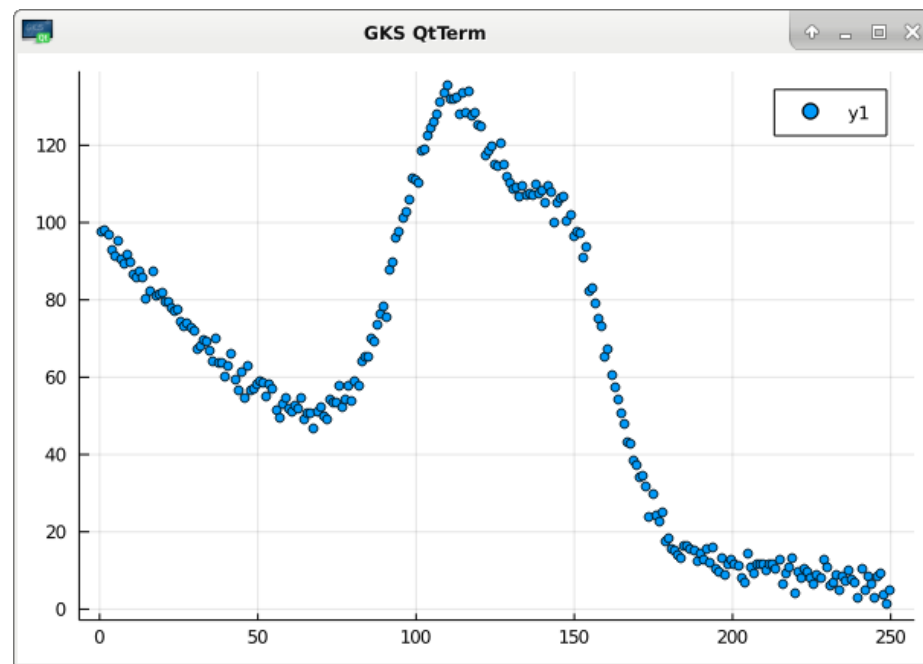
Solution: Find the 8 parameters using Monte-Carlo approach.



[1] <https://www.itl.nist.gov/div898/strd/nls/data/gauss3.shtml>

Example: Non-linear fitting (cont'd) using a Monte-Carlo method:

- 1) Generate N points of p (of dim $D=8$), with each element of p uniformly distributed in the corresponding dimension within its range;
- 2) For each point p , compute the error (a scalar)
 $z[i] = \|y - f(x;p)\|, i=1\dots N$
- 3) Sort z in ascending order, pick the first M corresponding points p as new candidates; find the minimum z_{\min} (and the best p);
- 4) Adjust the range for each dimension of p that encloses the M selected candidates;
- 5) If $z_{\min} \leq \text{tol}$ && $\text{iter} \leq \text{num_iters}$ STOP; else GOTO 1).



$$\begin{aligned} y &= f(x; p) \\ &= p_1 \exp(-p_2 x) \\ &+ p_3 \exp[-(x - p_4)^2 / p_5^2] \\ &+ p_6 \exp[-(x - p_7)^2 / p_8^2]. \end{aligned}$$



Example: Non-linear fitting (cont'd) using a Monte-Carlo method:

- 1) Generate N points of p (of dim D=8) , with each component of p uniformly distributed in corresponding dimension within its range;
- 2) For each point p, compute the error (a scalar)
 $z[i] = \|y - f(x;p)\|, i=1\dots N$
- 3) Sort z in ascending order, pick the first M corresponding points p as new candidates; find the minimum z_min (and the best p);
- 4) Adjust the range for each dimension of p that embraces the M selected candidates;
- 5) If z_min <= tol && iter <= num_iters STOP; else GOTO 1).

Sketch of serial code

```
while (z_min > tol && iters <= num_iters)
  # Generate N parameter points params[D,N]
  for i in 1:N
    params[:,i] = llims .+ rand(D).*intervals;
    z[i] = costfun(y,x,params[:,i],ym[:,i]);
  end
```

... ..

end

$$\text{param}[1:D,1:N] = \begin{bmatrix} p_1^{(1)} & p_1^{(2)} & \cdots & \cdots & p_1^{(N)} \\ p_2^{(1)} & p_2^{(2)} & \cdots & \cdots & p_2^{(N)} \\ \vdots & \vdots & & & \vdots \\ \vdots & \vdots & & & \vdots \\ p_D^{(1)} & p_D^{(2)} & \cdots & \cdots & p_D^{(N)} \end{bmatrix}$$



Example: Non-linear fitting (cont'd) using a Monte-Carlo method:

- 1) Generate N points of p (of dim $D=8$), with each component of p uniformly distributed in corresponding dimension within its range;
- 2) For each point p , compute the error (a scalar)
 $z[i] = \|y - f(x;p)\|$, $i=1\dots N$
- 3) Sort z in ascending order, pick the first M corresponding points p as new candidates; find the minimum z_{\min} (and the best p);
- 4) Adjust the range for each dimension of p that embraces the M selected candidates;
- 5) If $z_{\min} \leq \text{tol}$ && $\text{iter} \leq \text{num_iters}$ STOP; else GOTO 1).

Sketch of serial code

```
while (z_min > tol && iters <= num_iters)
  # Generate N parameter points params[D,N]
  for i in 1:N
    params[:,i] .= llims .+ rand(D).*intervals;
    z[i] = costfun(y,x,params[:,i],ym[:,i]);
  end

  # Sort the vector z and find the smallest one
  iz_sorted[:] = sortperm(z);
  iz_min = iz_sorted[1]; z_min = z[iz_sorted[1]];
  ... ..
end
```



Example: Non-linear fitting (cont'd) using a Monte-Carlo method:

- 1) Generate N points of p (of dim $D=8$), with each component of p uniformly distributed in corresponding dimension within its range;
- 2) For each point p , compute the error (a scalar)
 $z[i] = \|y - f(x;p)\|$, $i=1\dots N$
- 3) Sort z in ascending order, pick the first M corresponding points p as new candidates; find the minimum z_{\min} (and the best p);
- 4) Adjust the range for each dimension of p that embraces the M selected candidates;
- 5) If $z_{\min} \leq \text{tol}$ && $\text{iter} \leq \text{num_iters}$ STOP; else GOTO 1).

Sketch of serial code

```
while (z_min > tol && iters <= num_iters)
  # Generate N parameter points params[D,N]
  for i in 1:N
    params[:,i] .= llims .+ rand(D).*intervals;
    z[i] = costfun(y,x,params[:,i],ym[:,i]);
  end

  # Sort the z; pick the first M corresponding points of p
  iz_sorted[:] = sortperm(z);
  iz_min = iz_sorted[1]; z_min = z[iz_sorted[1]];
  elite_view = view(params[:,iz_sorted[1:num_elites]]);

  # Update the range of each of the parameters
  llims[:] = minimum(elite_view,dims=2);
  ulims[:] = maximum(elite_view,dims=2);
  intervals .= ulims .- llims;
  iter += 1;
end
```



Example: Non-linear fitting (cont'd) using a Monte-Carlo method:

- 1) Generate N points of p (of dim $D=8$), with each component of p uniformly distributed in corresponding dimension within its range;
- 2) For each point p , compute the error (a scalar)
 $z[i] = \|y - f(x;p)\|$, $i=1\dots N$
- 3) Sort z in ascending order, pick the first M corresponding points p as new candidates; find the minimum z_{\min} (and the best p);
- 4) Adjust the range for each dimension of p that embraces the M selected candidates;
- 5) If $z_{\min} \leq \text{tol}$ && $\text{iter} \leq \text{num_iters}$ STOP; else GOTO 1).

Sketch of parallel code using threads

```
while (z_min > tol && iters <= num_iters)
  # Generate N parameter points params[D,N]
  @threads for i in 1:N
    params[:,i] .= llims .+ rand(D).*intervals;
    z[i] = costfun(y,x,params[:,i],ym[:,i]);
  end

  # Sort the z; pick the first M corresponding points of p
  iz_sorted[:] = sortperm(z);
  iz_min = iz_sorted[1]; z_min = z[iz_sorted[1]];
  elite_view = view(params,:,iz_sorted[1:num_elites]);

  # Update the range of each of the parameters
  llims[:] = minimum(elite_view,dims=2);
  ulims[:] = maximum(elite_view,dims=2);
  intervals .= ulims .- llims;
  iter += 1;
end
```



Parallel computing: Starting multiple threads

From command line (ver 1.5 and newer)

```
julia -t 8
```

or

```
julia --threads 8
```

Or via environment variable

```
export JULIA_NUM_THREADS=8
```



- [1] Marc Marano Maza, Lecture Notes: Distributed and parallel systems, Department of Compute Science, Western University, 2017.
- [2] Julia documentations: <https://docs.julialang.org/en/v1/>.
- [3] Julia cheat sheet: <https://juliadocs.github.io/Julia-Cheat-Sheet/>.
- [4] Jeff Bezanson, Stefan Karpinski, *State of Julia*, JuliaCon 2020 (YouTube).

